# **Efficient Data Reduction and Summarization**

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# **Research Goals**

- 1. Developing fundamental algorithms for processing massive data
  - Massive high-dimensional data
  - High-speed dynamic streaming data
  - Massive sparse data
- 2. Applying these algorithms to data analytics and visualization
  - Scalable visualization algorithms.
  - Scalable Machine Learning algorithms.
  - Real-time network flow measurement algorithms.
- 3. Training Graduate/Undergraduate students

Some of the research goals were not included in the original proposal. Additional funding will be sought from other sources.

# The Era of Modern Massive Data

• There is no data like more data (Mercer at Arden House, 1985)

• More data is more important than better algorithms (Banko & Brill, ACL 2001)



#### FODAVA, Efficient Data Reduction and Summarization,



Highly successful workshop Funded by NSF and Yahoo!

• MMDS 2006, June, Stanford University

Ping Li, Trevor Hastie,

Efficient L2 and L1 dimension reduction in massive databases

MMDS 2008, June, Stanford University

Ping Li,

Compressed Counting and Stable Random Projections

# The Data Matrix

Data matrix  $\mathbf{A} \in \mathbb{R}^{n \times D}$ : *n* rows and *D* columns.



Examples: Term-doc matrix, Image-pixel matrix, etc.





Summarization is fundamental in learning, visualization, and linear algebra.

- Summary statistics of individual rows (or columns) eg,  $\alpha$ th moment  $\sum_{i=1}^{D} |u_i|^{\alpha}$ , entropy, etc.
- Summary statistics between rows (or columns) eg, dot products,  $\alpha$ th distance  $\sum_{i=1}^{D} |u_i - v_i|^{\alpha}$ ,  $\chi^2$  distance, etc.

#### Some challenges

- Memory intensive Loading  $\mathbf{A} \in \mathbb{R}^{n \times D}$  may be infeasible. Loading all pairwise (eg,  $n^2$ ) distances of  $\mathbf{A}$  can be easily infeasible.
- CPU intensive
- Dynamic updating

### From Exact Answers to Approximations

(Good) Approximate summary statistics (eg distances) often suffice

- Visualization systems only need a certain resolution.
- Good (robust) algorithms are stable even using approximate inputs.

Simple random sampling (eg using a few columns) is not enough

- Not accurate.
- Not suitable for sparse data.

## **Three Basic Approximation Techniques**

1. Symmetric Stable Random Projections

Computing  $\alpha$ th distances ( $0 < \alpha \le 2$ ) of data matrix.  $\alpha = 2$ : Euclidean distance.  $\alpha = 0$ : Hamming distance.

Applicable to dynamic streaming data in Turnstile model.

- 2. Compressed Counting (CC) (Skewed Stable Random Projections) Computing  $\alpha$ th moments ( $0 < \alpha \le 2$ ) of data stream in strict-Turnstile model.
- 3. Conditional Random Sampling (CRS) One-sketch-for-all

Computing any type of distances or moments Applicable to more general dynamic data Only works well in sparse data

# Symmetric Stable Random Projections



- Original data matrix A ∈ ℝ<sup>n×D</sup>: n rows and D columns, Massive, eg, both n, D = O (10<sup>10</sup>).
   Possibly dynamic, according to the Turnstile model.
- Projection matrix  $\mathbf{R} \in \mathbb{R}^{D \times k}$ : D rows and k columns,  $k \ll n, D$ Entries are samples of a symmetric  $\alpha$ -stable distribution.  $\alpha = 2$ : Normal distribution.  $\alpha = 1$ : Cauchy distribution.
- Projected matrix  $\mathbf{B} \in \mathbb{R}^{n \times k}$ : *n* rows and *k* columns Viewed as a sketch of **A**, which may be discarded.

## Symmetric $\alpha$ -Stable Distributions

Denoted by  $S(\alpha, d)$ , where  $0 < \alpha \le 2$ .

Two random variables  $Z_1 \sim S(\alpha, 1)$  and  $Z_2 \sim S(\alpha, 1)$ .

For any constants  $C_1$  and  $C_2$ 

$$Z = C_1 \times Z_1 + C_2 \times Z_2 \sim S(\alpha, |C_1|^{\alpha} + |C_2|^{\alpha})$$

For example, weighted sum of normals is also normal ( $\alpha = 2$ ).



Therefore, the projected matrix **B** contains information about

1. 
$$\alpha$$
th moment,  $\sum_{i=1}^{D} |u_i|^{\alpha}$ , of each row of **A**.

2.  $\alpha$ th distance,  $\sum_{i=1}^{D} |u_i - v_i|^{\alpha}$ , between any two rows of **A**.

# **Applications of Symmetric Stable Random Projections**

#### • Data visualization algorithms

Multi-dimensional scaling (MDS) requires a pairwise similarity matrix.

### • Machine Learning algorithms

SVM (support vector machine) requires a  $O(n^2)$  pairwise distance matrix.

#### • Information retrieval

Finding (filtering) nearly duplicate docs (often measured by distance)

#### • Databases

Estimating join sizes (dot products) for optimizing query execution.

#### Dynamic data stream computations

Estimating summary statistics for visualizing/detecting anomaly real-time

An incomplete list of references:

- Vempala 2004. A monograph focused on  $\alpha = 2$ .
- Alon, Matias, and Szegedy, 1996, STOC
- Indyk, 2006, JACM
- Li, Hastie, and Church, 2006, KDD
- Li, Hastie, and Church, 2006, COLT
- Li, 2007, KDD
- Li, Hastie, and Church, 2007, COLT
- Li and Hastie, 2008, NIPS
- Li, 2008, SODA

A lot have been done, and a lot more to do!

### 1. Theory

- Statistically optimal recovery (estimation) methods
- Computationally efficient estimation methods.

### 2. Applications

- Building scalable data visualization algorithms (eg, MDS).
- Building scalable machine learning algorithms (eg, SVM).
- 3. Connection to Compressed Sensing (CS)

CS uses  $\alpha = 2$  (normal) random projections.

Can we use general  $\alpha$ th projections for sparse signal recovery?

# **Compressed Counting (CC)**

A new methodology recently invented

- Preliminary results: Li, Compressed Counting, SODA 2009.
- Based on skewed stable random projections.
- Applicable to dynamic data streams following strict-Turnstile model.
- Achieving an "infinite" improvement over symmetric projections when  $\alpha \approx 1$ .
- Applications in estimating entropy real-time for network anomaly detections.

### **Turnstile Data Stream Model**

At time t, an incoming element :  $a_t = (i_t, I_t)$  $i_t \in [1, D]$  index,  $I_t$ : increment/decrement.

Updating rule : 
$$A_t[i_t] = A_{t-1}[i_t] + I_t$$

Goal : Count  $\alpha$ th moment  $F_{(\alpha)} = \sum_{i=1}^{D} A_t[i]^{\alpha}$ 

Strict-Turnstile model :  $A_t[i] \ge 0$  always, suffices for almost all applications.



Goal : Count 
$$F_{(lpha)} = \sum_{i=1}^D A_t[i]^{lpha}$$
, where  $\left| A_t[i_t] = A_{t-1}[i_t] + I_t \right|$ 

When  $\alpha \neq 1$ , counting  $F_{(\alpha)}$  exactly requires D counters. (but D can be  $2^{64}$ )

When  $\alpha = 1$ , however, counting the sum is trivial, using a simple counter.

$$F_{(1)} = \sum_{i=1}^{D} A_t[i] = \sum_{s=1}^{t} I_s,$$

Compressed Counting (CC) captures this intuition

Symmetric stable random projections totally ignore this fact.



# Skewed $\alpha$ -Stable Distributions

Denoted by  $S(\alpha, \beta, d)$ .  $\beta = 0$ : symmetric,  $\beta = 1$ , maximally-skewed.

Two random variables  $Z_1 \sim S(\alpha, \beta, 1)$  and  $Z_2 \sim S(\alpha, \beta, 1)$ .

For any constants  $C_1 \geq 0$  and  $C_2 \geq 0$ 

$$Z = C_1 \times Z_1 + C_2 \times Z_2 \sim S\left(\alpha, \beta, \frac{C_1^{\alpha}}{1} + \frac{C_2^{\alpha}}{2}\right)$$

CC works only for strict-Turnstile model.

# **One Application of CC: Entropy Measurement**

#### The Shannon entropy:

- An extremely useful measurement in network data flow. Monitoring/visualizing network anomaly.
- Real-time measure is critical.
- It can be approximated by functions of  $\alpha$ th moments with  $\alpha \rightarrow 1$ .
- Therefore, CC becomes very useful.

## **Research Topics for Compressed Counting**

### 1. Theory

- Improved estimation methods with better convergence rate as  $\alpha \rightarrow 1$ .
- Computationally efficient estimation methods.
- Computationally efficient methods for sampling skewed distributions.

### 2. Applications

eg, practically efficient entropy estimation.

3. Connection to Compressed Sensing (CS)

CC has recently attracted attention in CS community.

## **Limitations of Random Projections**

1. Ignoring data sparsity

eg, text data, histogram-based data

2. Applicable only to a particular  $\alpha {\rm th}$  moment.

Different projections for different  $\alpha$ 's.

- 3. Not applicable to many other summary statistics eg  $\chi^2$  distance.
- 4. Applicable only to Turnstile data stream model  $A_t[i] = A_{t-1}[i] + I_t$ but real-world may need nonlinear updating rules.

Conditional Random Sampling (CRS) provides a fix and works well in sparse data.

# **Conditional Random Sampling (CRS): Progress**

- Li and Church, EMNLP, 2005
- Li and Church, Computational Linguistics, 2007
- Li, Church, and Hastie, NIPS, 2007
- Li, Church, and Hastie, NIPS, 2009

# Th Sketching Procedure of CRS

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### Inverted Index (Nonzeros)



### Random Permutation on Columns



#### Sketches (Front of inverted index)



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# **Research Topics of CRS**

### 1. Theory

- The current algorithm is basically a (very good) heuristic. The exact solution is a difficult classical statistical problem.
- Improved estimation methods using side information.

### 2. Applications

- Scalable data visualization algorithms.
- Scalable machine learning algorithms.
- Maintaining multi-way histograms.
- General data stream applications.
- 3. Combining CRS with random projections

# How Will This Influence FODAVA? Broader Impact?

Possibly all data analytics and visualization techniques need to address

- How to feasibly store massive data in a compact format?
- How to update the data in dynamic settings?
- How to compute summary statistics (distances) efficiently or real-time?

#### **Broader Impact:**

- Scalable machine learning
- Databases and information retrieval
- Network measurement
- (Possibly) sparse signal recovery (compressed sensing)

