

Carnegie Mellon University Silicon Valley

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Visualization of Analytical Processes

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Georgia Tech

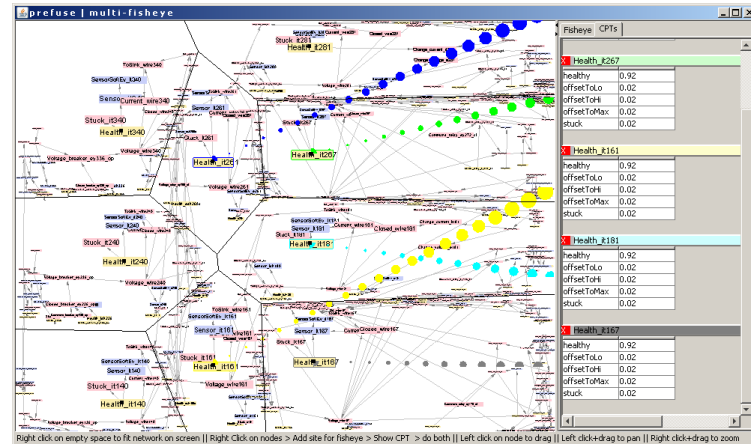
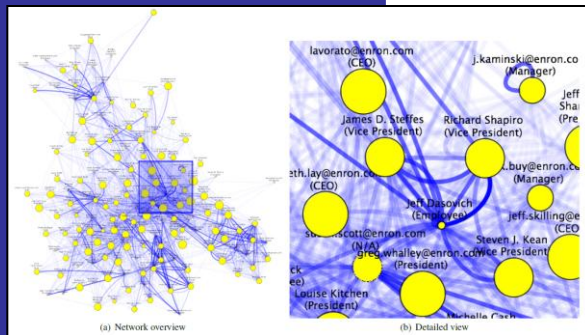
Project Overview

Goal: Improve the visualization of analytical processes, in particular for probabilistic graphical (Bayesian network) models and other networks models.

Timeline: 2009-2011
(currently no-cost extension)



Faculty:
Mengshoel,
Selker, and Ilic



Areas of Research

Probabilistic and statistical models, algorithms:

Probabilistic graphical models: Bayesian networks, ...

Inference: Diagnosis, prognosis, ...

Machine learning

Interactive visualization:

Network visualization

Multi-view, Multi-focus, ...

Stochastic and randomized algorithms:

Stochastic local search

Evolutionary algorithms

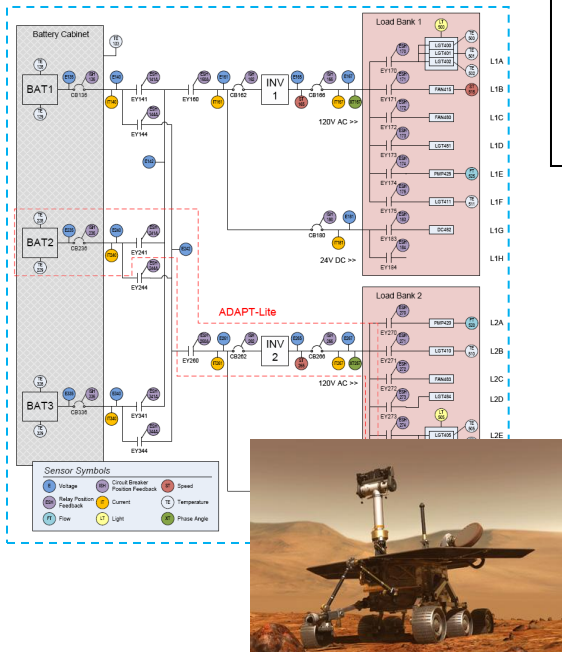
Applications and demonstrations:

Challenging and large-scale applications, multi-media data sets, ...

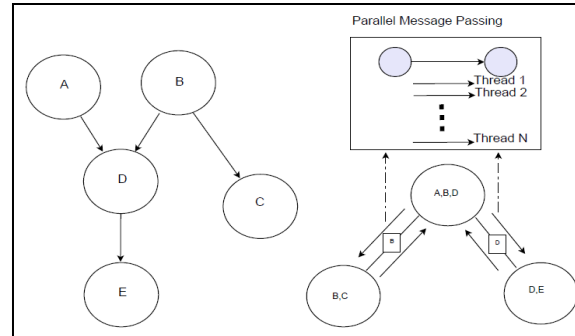
Scalability of algorithms, visualizations, user interactions, ...

Research Directions

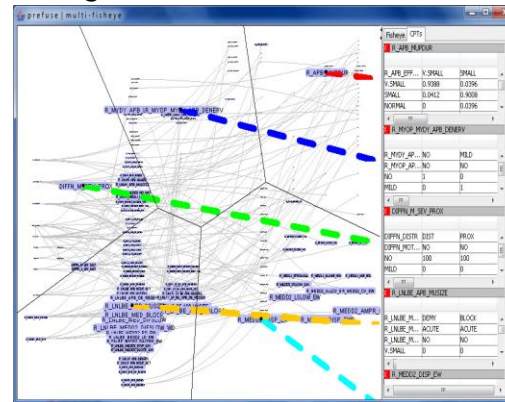
Electrical Power System Diagnosis using Probabilistic Computation



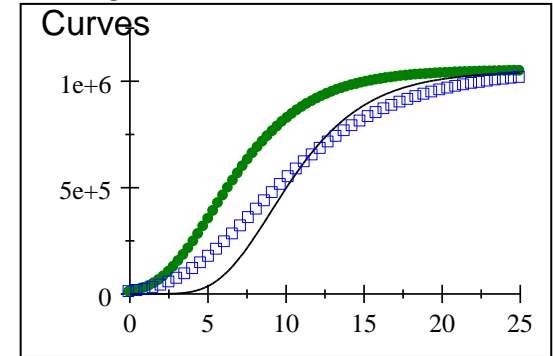
Fast Belief Propagation Using GPU Parallelization in Junction Trees



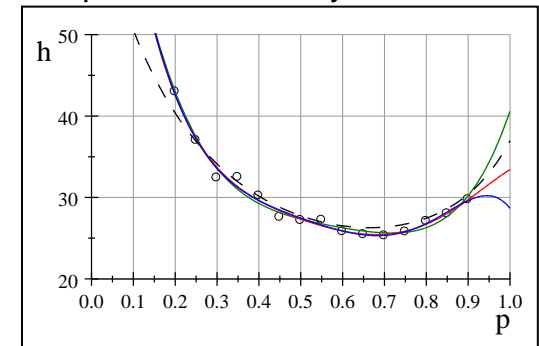
Multi-Fisheye, Multi-View for Interactive Visualization of Large Networks



Understanding Scalability of Bayesian Network Computation using Junction Tree Growth

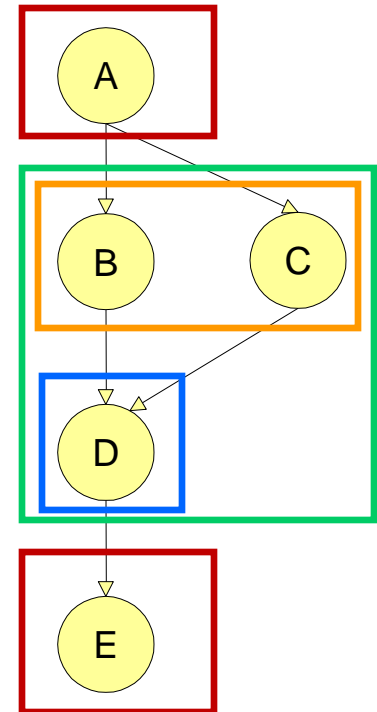


Stochastic Search for Computing Most Probable Explanations in Bayesian



Bayesian Network Inference

- Bayesian network inference answers these queries:
 - *Marginal/MLV*: Given **evidence** at some nodes, infer posterior probability/most likely value (MLV) over **one node**
 - *Most probable explanation (MPE)*: Given **evidence**, find explanation with greatest probability over **remaining nodes**
 - *Maximum a posteriori probability (MAP)*: Given **evidence**, find explanation with greatest probability over **some nodes**
- Computational hardness [Cooper, 1990; Shimony, 1994; Roth 1996]:
 - Care is needed, in modeling, machine learning, and inference
- Inference algorithms:
 - *Exact*: Clique tree propagation [Lauritzen & Spiegelhalter, 1988]; Arithmetic circuit evaluation [Darwiche, 2003; Darwiche & Chavira, 2007]; ...
 - *Approximate*: Stochastic local search [Kask & Dechter, 1999; Mengshoel, 1999; Mengshoel 2008]; Variational inference; ...



Need for Resilient Operations and System Health Management

On September 2, 1998, Swissair 111 crashed into the Atlantic Ocean, killing all 229 people onboard. Probably, *wires short-circuited* and led to a fire.

A *battery failure* occurred on the Mars Global Surveyor on November 2, 2006. A *software error* caused the battery to overheat due to over-exposure to sunlight.

In 1999, the Mars Polar Lander crashed into the surface of Mars, most likely due to a premature engine shutdown because of *spurious lander leg signals*.

For the Mars rover SPIRIT, a *full on-board file system* caused reboot-loop after landing.

On June 4, 1996, software on the Ariane V rocket, reused from Ariane IV, *overflowed* and lead to its destruction.



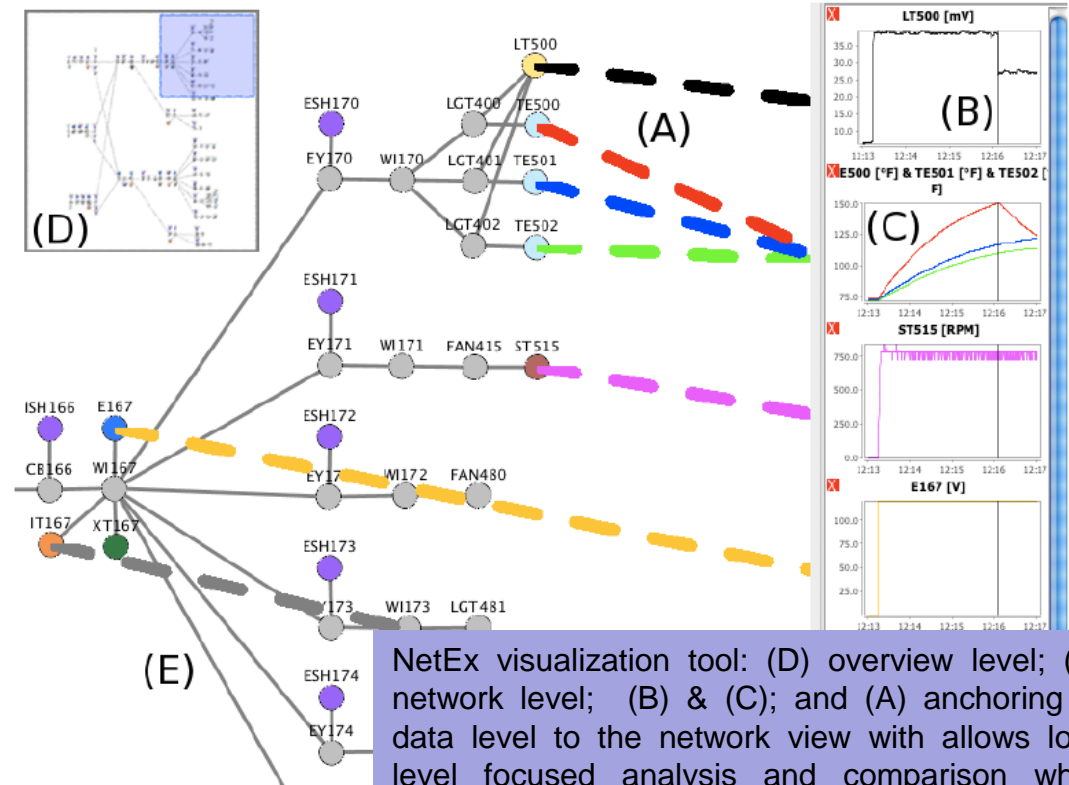
Multi-View Overview+Detail for Networks

OBJECTIVE

Making multiple and multi-step comparisons across different parts of a data corpus and across multiple representational levels in a complex data set.

FEATURES

- Visual encoding of data properties
- Overview + detail
- Multi-focus + context
- Bubbles anchoring node information to the network



NetEx visualization tool: (D) overview level; (E) network level; (B) & (C); and (A) anchoring of data level to the network view with allows low-level focused analysis and comparison while preserving network structure.

RESULTS

In experiments with data from an electrical power network we demonstrated how NetEx makes fault diagnosis easier. Results from a **user study** with 25 subjects suggests that NetEx enables more accurate isolation of faults in multi-fault situations.

Multi-View Focus+Context for Networks

OBJECTIVE

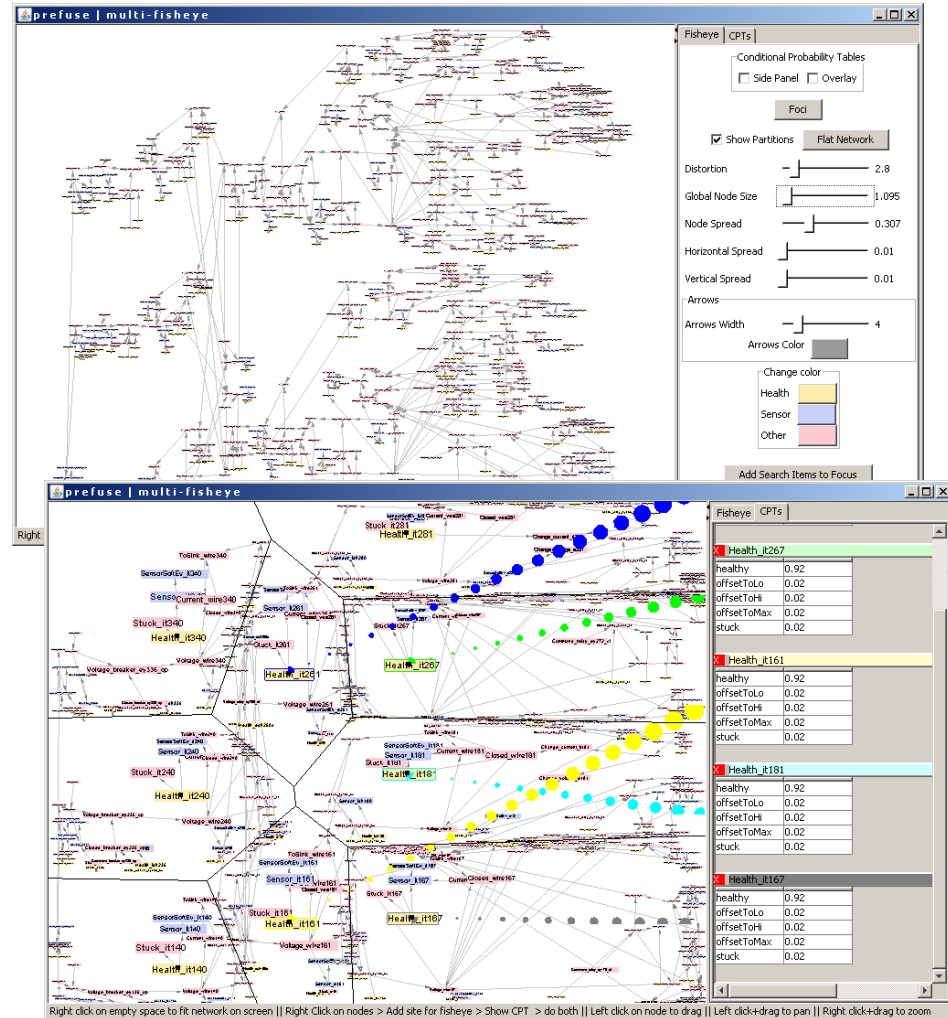
Improve the applicability of multi-fisheye to exploration of labeled networks, including Bayesian network (BN) problem instances. Focus on large-scale but in-memory networks.

DESCRIPTION

A focus+context visualization tool that supports visualization of multiple fisheye distortions in network (Bayesian networks, for example). Voronoi edges separate the fisheyes, and data boxes with details (such as Bayesian network conditional probability tables) are created for fisheyes and their neighboring nodes.

RESULTS

The tool supports interactive and simultaneous creation of up to 10-20 readable node labels by means of fisheye distortion in large-scale (Bayesian) networks. Node context, including network edge connection patterns and relative location, is preserved.



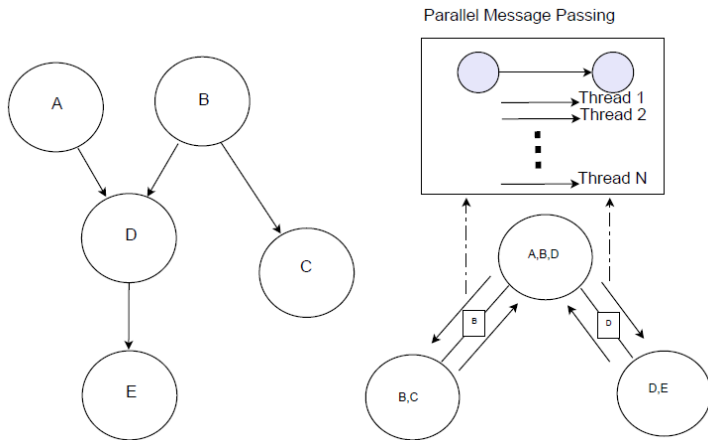
Belief Propagation by Fast GPU Message Passing in Junction Trees

OBJECTIVE

Speed up Bayesian network computation when junction trees are being used; use graphics processing units (GPUs).

DESCRIPTION

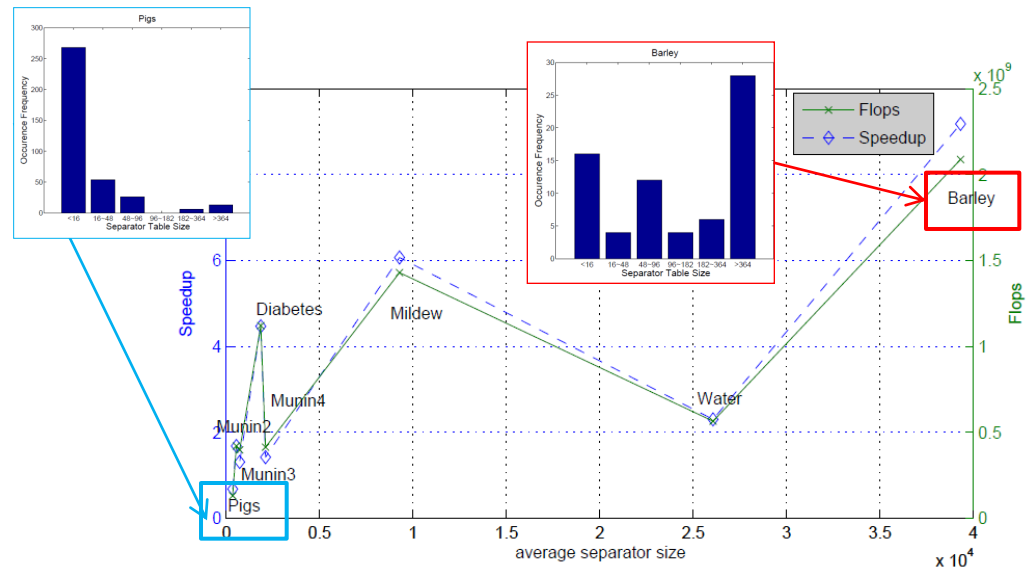
An algorithm in which message passing is performed in parallel, benefiting situations with large cliques and large separators



RESULTS

Analytical and experimental speed up – best experimental speed up result to date is 918%.

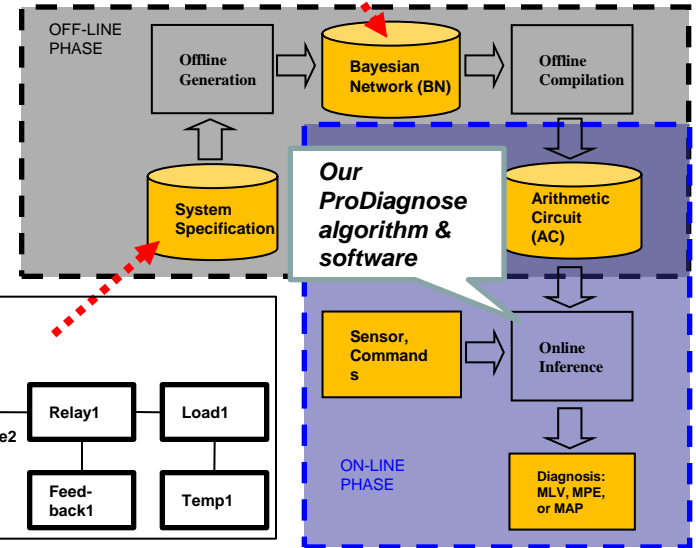
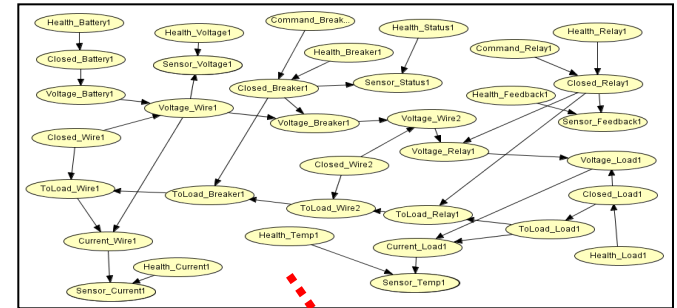
$$Speedup = \frac{\sum_i \sum_{k \in Ne(c_i)} (|\phi_{x_i}| + |\phi_{x_k}|)}{2(n-1)\tau + \sum_i \sum_{k \in Ne(c_i)} \frac{(|\phi_{x_i}| + |\phi_{x_k}|)}{|\phi_{s_{ik}}|}}$$



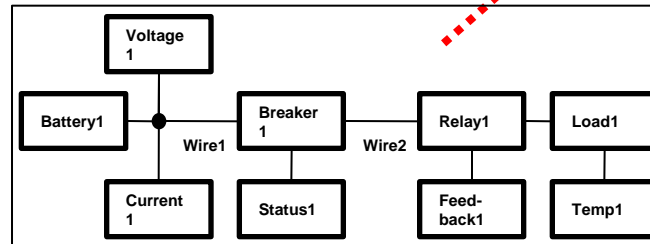
Bayesian Methods for Diagnostics (1)

Goal: Tackle system health management and diagnostic challenges:
Large & complex systems; Hybrid systems (discrete & continuous behavior); Hard diagnostic problems; Real time requirements.

Approach: Develop probabilistic diagnosis approach, ProDiagnose: Auto-generation of Bayesian network; Compilation of Bayesian networks to real-time arithmetic circuits; Diagnose discrete and continuous faults on-line.

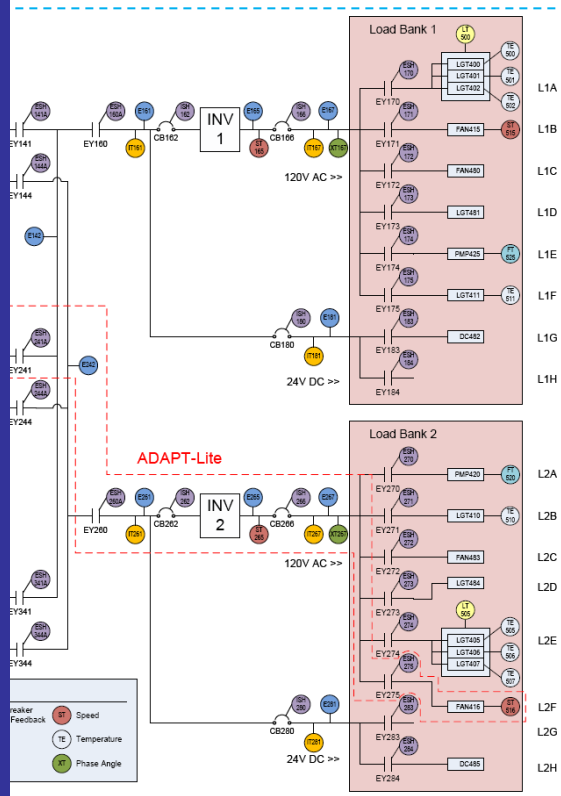


Electrical Power System



Bayesian Methods for Diagnostics (2)

ADAPT – Electrical power system testbed at NASA ARC.



Two conditions:
Our novel cumulative sum (CUSUM) technique (i) enabled or (ii) disabled.

Metric	CUSUM	
	Enabled	Disabled
Detection Accuracy	92.31%	46.15%
False Positives Rate	0%	0%
False Negatives Rate	8.82%	61.76%
Mean Time To Detect	17.97 s	28.36 s
Mean Time To Isolate	72.27 s	51.14 s

Bayesian Reasoning for Diagnostics:
Operates in a state space of size $> 2^{500}$
in time < 1 ms.

GPUs for Speeding up Bayesian Network Computation

Parallel and Distributed Computing

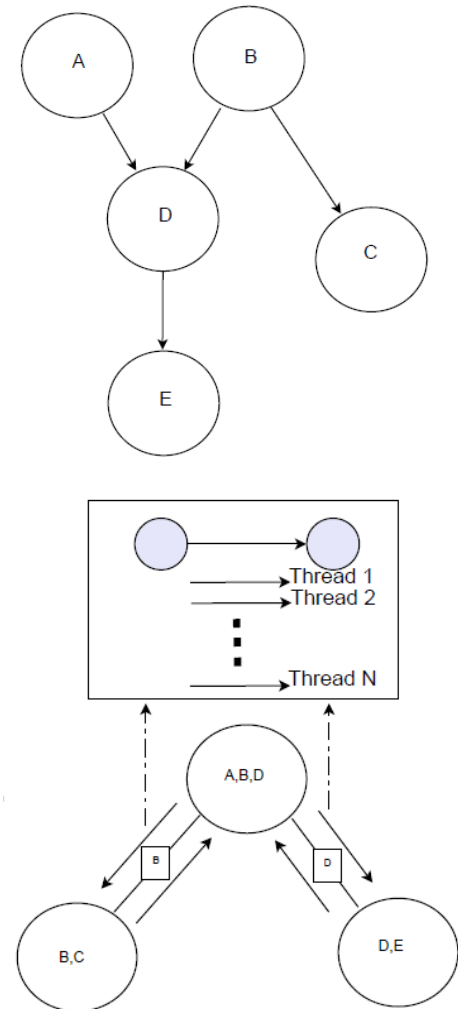
Graphics processing units (GPUs): Promise to dramatically up the performance of processing in the cloud and on the mobile device.

Speed up performance of processing in the cloud – integration with analytics software.

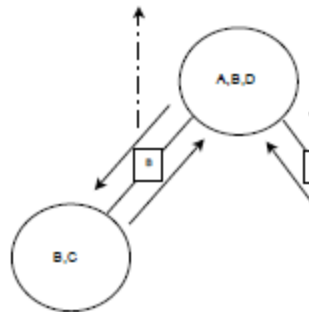
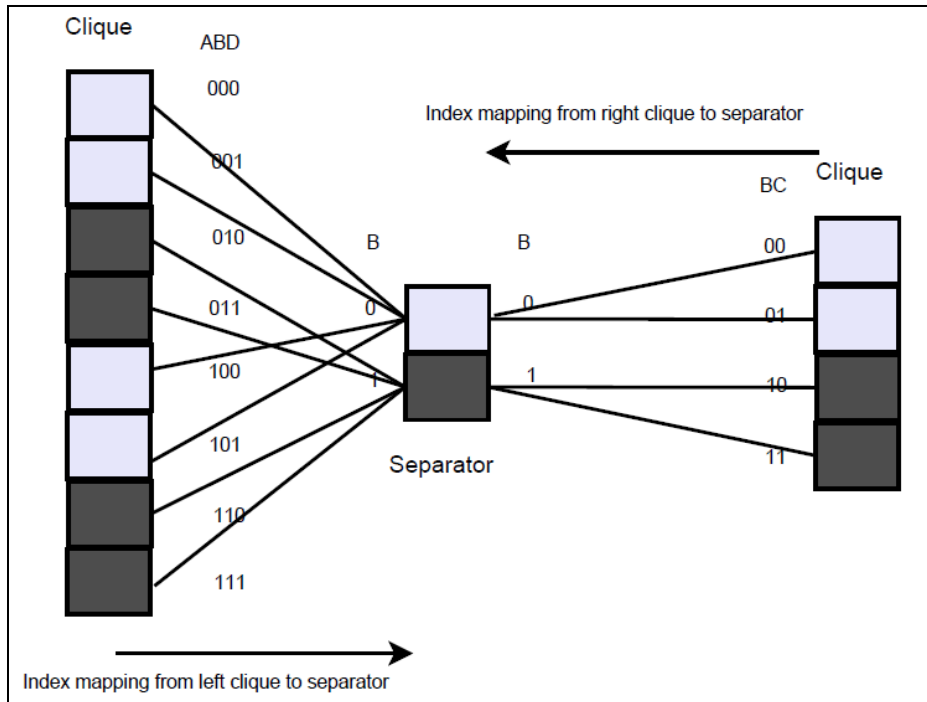
GPUs are moving onto mobile devices, and within the next year or two we expect them to be programmable through CUDA or other programming languages.

Motivation and Approach

- Belief propagation in junction trees may be computationally intensive due to:
 - The topology and connectedness of Bayesian networks
 - High cardinality of one or more nodes in cliques with sufficiently high number of nodes
- Observations:
 - During message passing, computations associated with different separator tables are independent
 - Some junction trees contain large cliques and separators
- Our approach:
 - Compute each message in parallel
 - Substantial parallelism opportunity when neighboring cliques and separators are large
 - Non-invasive embedding in original junction tree message passing algorithms



Fast Message Passing



Step 1: Marginalization

$$\phi_{\mathcal{S}_{ik}}^* = \sum_{\mathcal{X}_i / \mathcal{S}_{ik}} \phi_{\mathcal{X}_i}$$

Step 2: Scattering

$$\phi_{\mathcal{X}_k}^* = \phi_{\mathcal{X}_k} \frac{\phi_{\mathcal{S}_{ik}}^*}{\phi_{\mathcal{S}_{ik}}}$$

GPU Message Computation and Speedup

Algorithm 1 *Message_Passing*($\phi\mathcal{X}_i, \phi\mathcal{X}_k, \phi\mathcal{S}_{ik}$)

Input: $\phi\mathcal{X}_i, \phi\mathcal{X}_k, \phi\mathcal{S}_{ik}$.

for $j = 1$ *to* $|\phi\mathcal{S}_{ik}|$ **in parallel do**

 sep_star=0;

for $n = 1$ *to* $|\mu\mathcal{X}_{i,s_j}|$ **do**

 sep_star[j] = sep_star[j] + $\phi\mathcal{X}_i(\mu\mathcal{X}_{i,s_j}[n])$

end for

for $n = 1$ *to* $|\mu\mathcal{X}_{k,s_j}|$ **do**

$\phi\mathcal{X}_k(\mu\mathcal{X}_{k,s_j}[n]) = \frac{\text{sep_star}[j]}{|\phi\mathcal{S}_{ik}[j]|} \phi\mathcal{X}_k(\mu\mathcal{X}_{k,s_j}[n])$

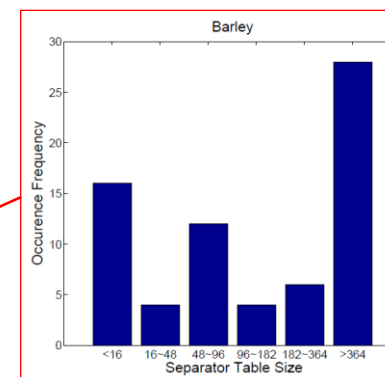
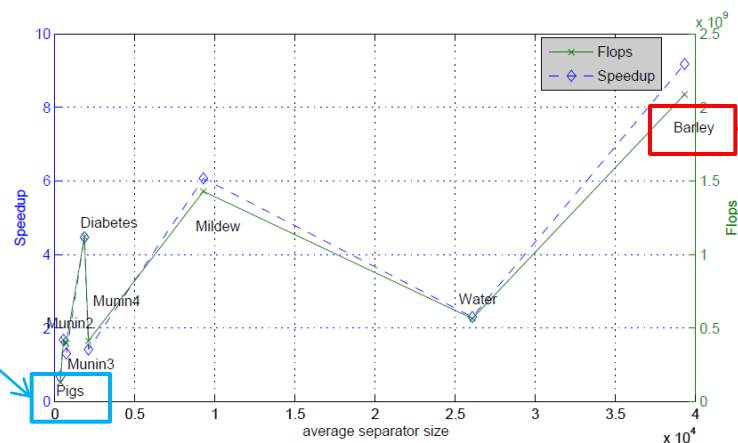
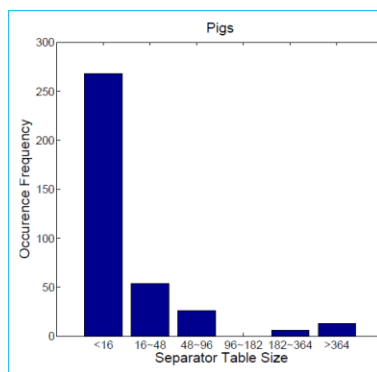
end for

end for

$$\text{Speedup} = \frac{\sum_i \sum_{k \in Ne(\mathcal{C}_i)} (|\phi\mathcal{X}_i| + |\phi\mathcal{X}_k|)}{2(n-1)\tau + \sum_i \sum_{k \in Ne(\mathcal{C}_i)} \frac{(|\phi\mathcal{X}_i| + |\phi\mathcal{X}_k|)}{|\phi\mathcal{S}_{ik}|}}.$$

GPU Parallelization: Experiments

Dataset	Mildew	Diabetes	Barley	Pigs	Munin2	Munin3	Munin4	Water
# of JT nodes	28	337	36	368	860	904	872	20
Max. CPT size	4,372,480	190,080	7,257,600	177,147	504,000	156,800	784,000	995,328
Min. CPT size	336	495	216	27	4	4	4	9
Ave. CPT size	341,651	32,443	512,044	1,927	5,653	3,443	16,444	173,297
Max. SPT size	71,680	11,880	907,200	59,049	72,000	22,400	112,000	147,456
Min. SPT size	72	16	7	3	2	2	2	3
Ave. SPT size	9,273	1,845	39,318	339	713	553	2,099	26,065
BP on GPU [ms]	53	94	106	75	125	104	342	52
BP on CPU [ms]	355	397	974	51	210	137	473	120
Speedup	6.70	4.22	9.19	0.68	1.68	1.32	1.38	2.31

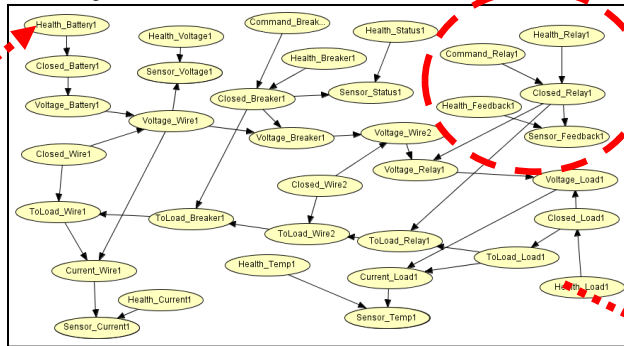


System Health Management using Bayesian Networks

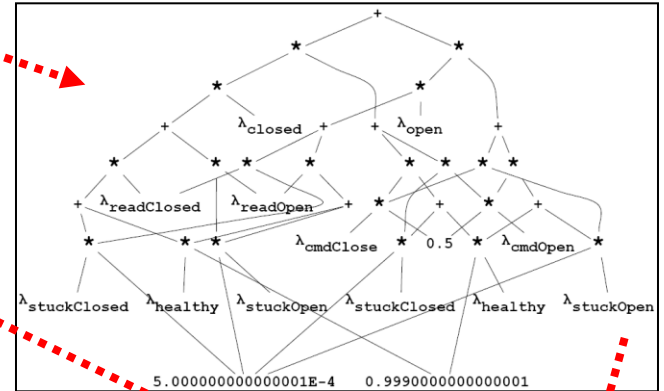
Architecture using Bayesian Networks

Each health variable has at least two states (healthy and faulty), thus enabling the diagnoses of zero, one, two, or more faults.

Bayesian network

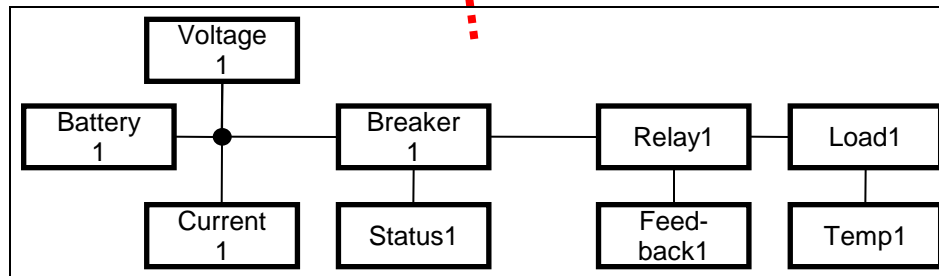
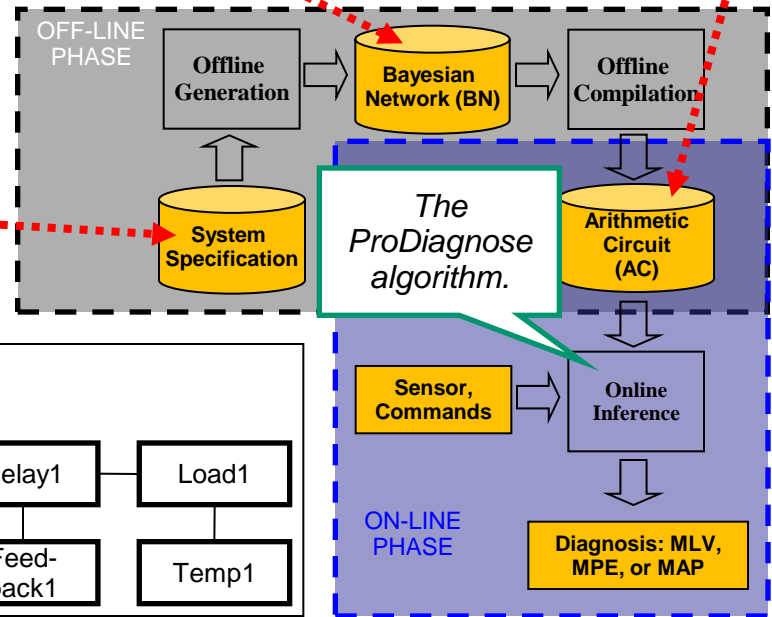


Arithmetic circuit



Specification language

Battery1	: battery	: 0.0005;
Wire1	: wire	: 0.0000 : Battery1;
Voltage1	: sensorVoltage	: 0.0005 : Wire1;
Current1	: sensorCurrent	: 0.0005 : Wire1;
Breaker1	: breaker	: 0.0005 : Wire1;
Status1	: sensorTouch	: 0.0005 : Breaker1;
Wire2	: wire	: 0.0000 : Breaker1;
Relay1	: relay	: 0.0005 : Wire2;
Feedback1	: sensorTouch	: 0.0005 : Relay1;
Load1	: load	: 0.0005 : Relay1;
Temp1	: sensorCurrent	: 0.0005 : Load1;



Fault Types

Independent faults

- Abrupt
 - Permanent
 - Discrete
 - Continuous (parametric)
- Intermittent
- Drift (incipient)

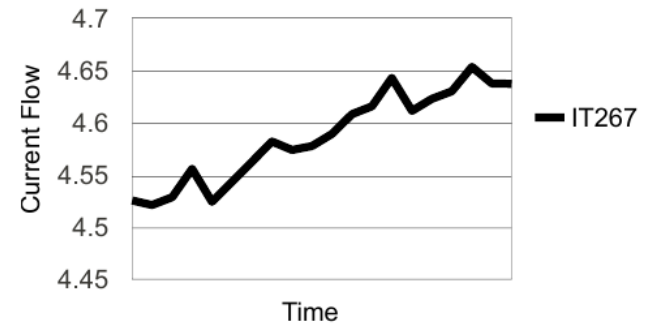
Dependent faults

- Common cause
- Cascading

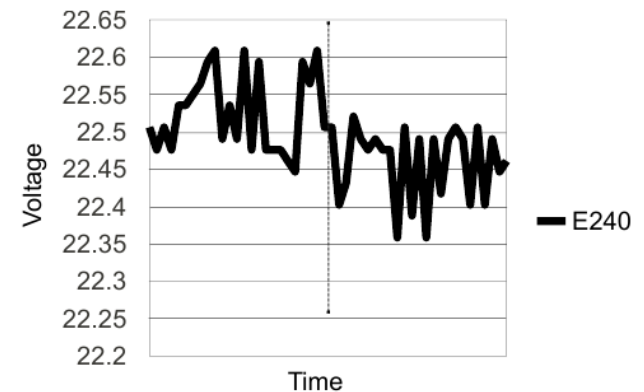
Bayesian networks in general

Problem-1 (DP1) and Problem-2 (DP2) of diagnostics challenge

Continuous drift fault



Continuous abrupt (offset) fault



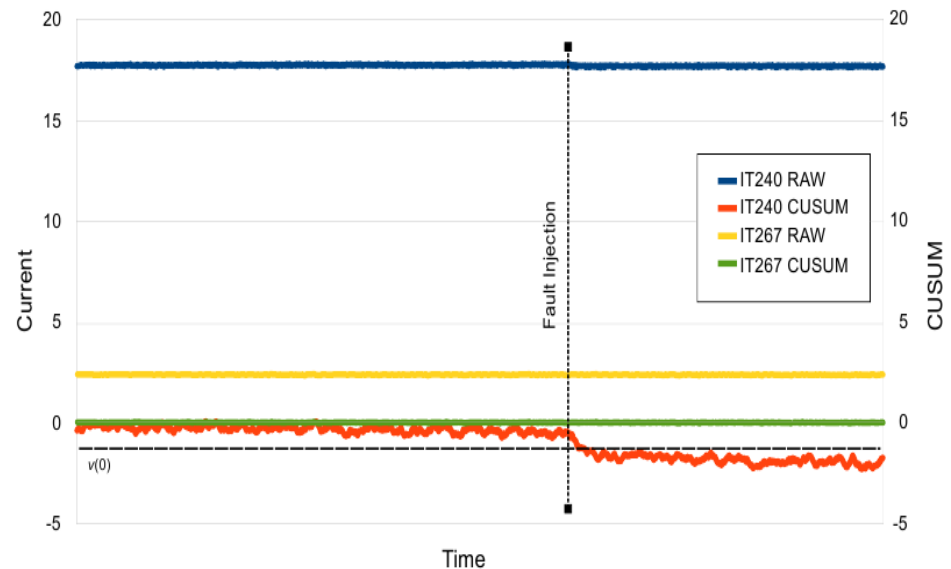
Cumulative Sum (CUSUM)

Mathematical definition of CUSUM:

$$\delta_p(t) = [s_p(t) - s_p(t - 1)] + \delta_p(t - 1)$$

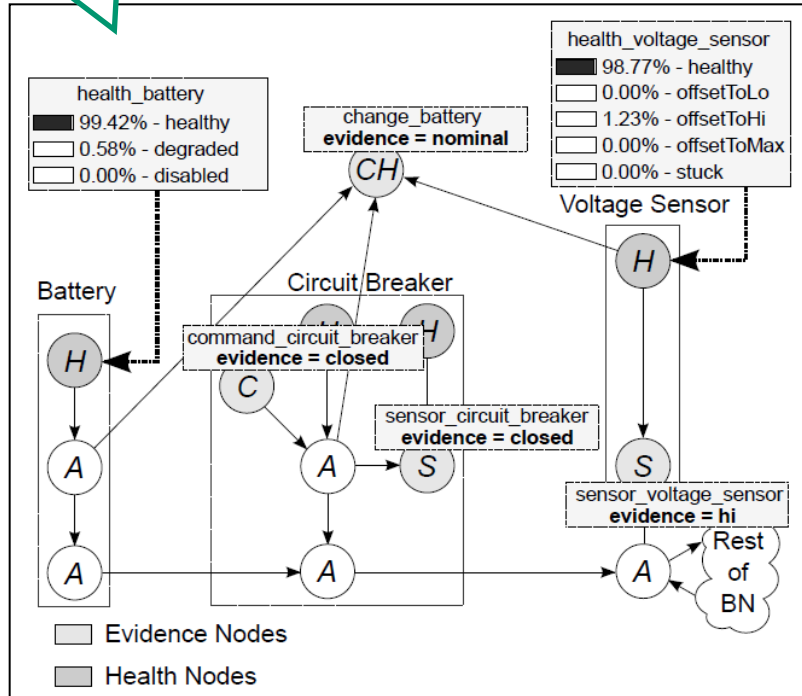
Graph illustrating CUSUM on current readings:

- The blue and orange plots represent the raw sensor readings (span of 4 minutes)
- The red and green plots represent the CUSUM values of these respective raw sensor readings
- The vertical dotted line represents the time of fault injection.
- Benefit of CUSUM: It [redacted] and [redacted] signals of [redacted] faulty [redacted]

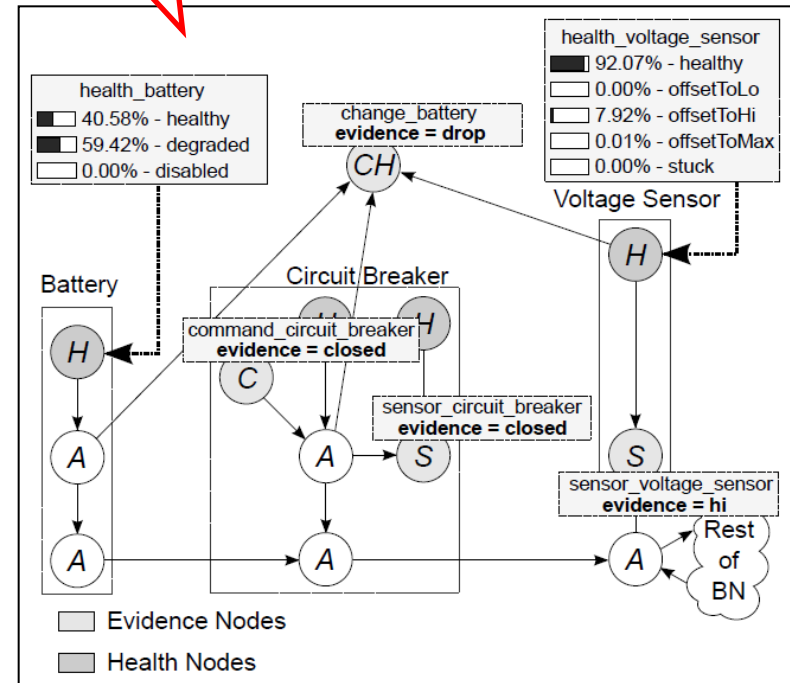


CUSUM – Continuous Offset Faults

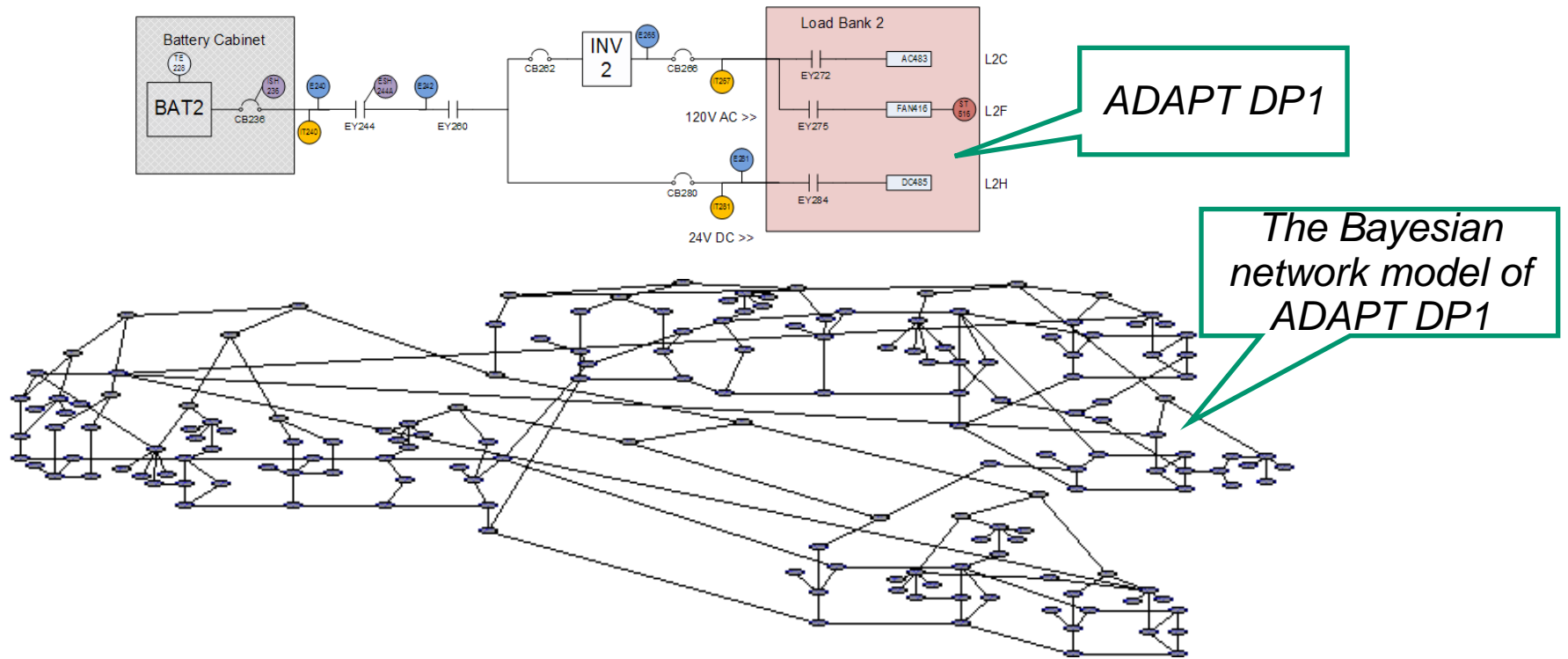
Nominal case



Fault case



Experimental Bayesian Network



Summary Statistics:

- DP1 Bayesian network:
 - Nodes: 148
 - Edges: 176
 - Cardinality: [2, 10]

Hypothesis: Similar networks can be constructed (by expert, machine learning, or combination) to detect, diagnose, predict, and mitigate in a broad range of systems.

Experiments, Simulated ADAPT Data

Inference Time (ms)	MPE		Marginals	
	VE	ACE	JTP	ACE
Minimum	19.30	0.2235	9.792	0.5721
Maximum	40.21	2.5411	65.34	5.9228
Median	19.81	0.2260	10.52	0.6006
Mean	20.13	0.2625	11.01	0.7854
St. Dev.	1.554	0.2028	4.101	0.6970

ACE is the approach used in ProDiagnose

Comparison between Arithmetic Circuit Evaluation (ACE), Variable Elimination (VE) and Clique Tree Propagation (CTP)

Main conclusions:

- All three inference algorithms are quite efficient, thanks to auto-generation algorithm
- ACE outperforms VE (for MPE) and CTP (for marginals), both in Mean and St. Dev.

Experiments, ADAPT Power System

Results summary (CUSUM enabled):

- DXC-10 training set
- Detection accuracy doubled
- False negative rate greatly improved
- Improvement in average detection time
- Average isolation time increased
 - The DX competition specifies that no isolation time be recorded for an incorrect mis-diagnosis.

	CUSUM	
Metric	Enabled	Disabled
Detection Accuracy	92.31%	46.15%
False Positives Rate	0%	0%
False Negatives Rate	8.82%	61.76%
Mean Time To Detect	17.97 s	28.36 s
Mean Time To Isolate	72.27 s	51.14 s

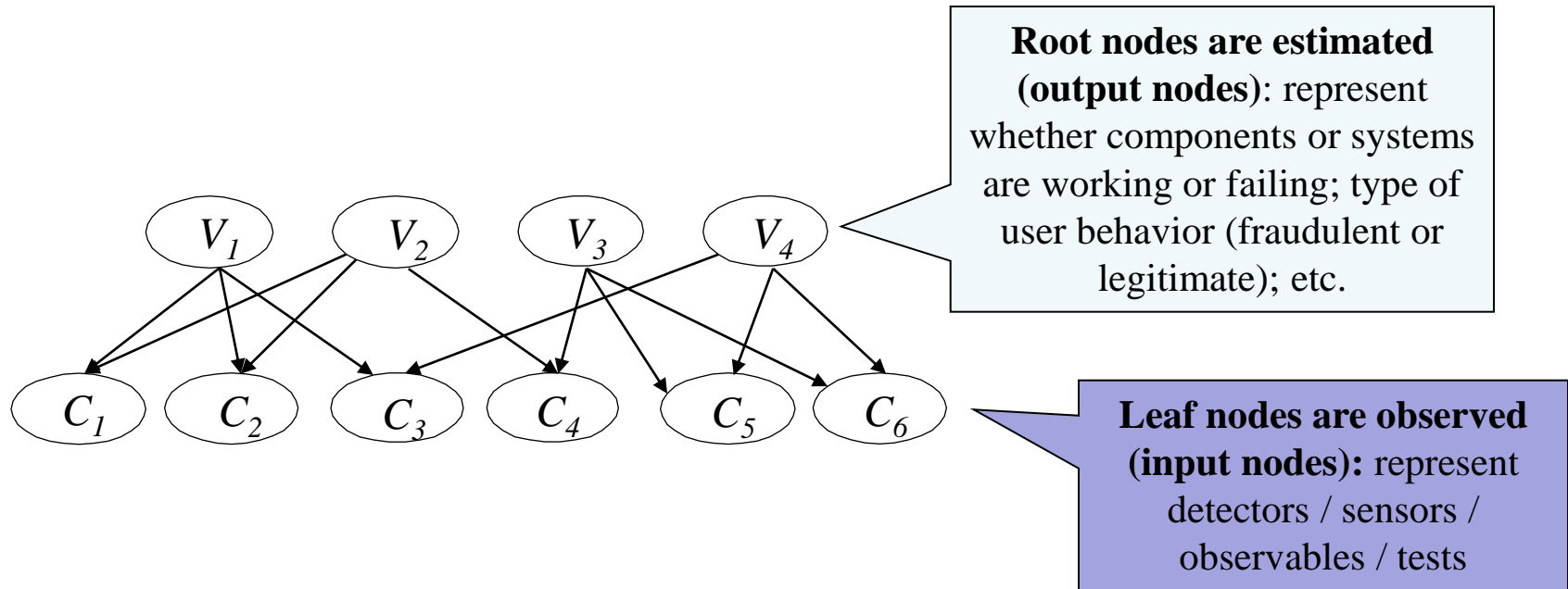
Metric	ADAPT DXC Tier 1			ADAPT DXC Tier 2		
	ProADAPT	RODON	HyDE-S	ProADAPT	Stanford	RODON
False positives (FP) rate	0.0333	0.0645	0.2000	0.0732	0.3256	0.5417
False negatives (FN) rate	0.0313	0.0968	0.0741	0.1392	0.0519	0.0972
Detection accuracy	0.9677	0.9194	0.8548	0.8833	0.8500	0.7250
Classification errors	2.0	10.0	26.0	76.0	110.5	84.1
Mean time to detect T_d (ms)	1,392	218	130	5981	3946	3490
Mean time to isolate T_i (ms)	4,084	7,205	653	12,486	14,103	36,331
Mean CPU time T_c (ms)	1,601	11,766	513	3,416	963	8,0261
Mean peak memory usage (kb)	1,680	26,679	5,795	6,539	5,912	29,878
Score	72.80	59.85	59.50	83.20	81.50	70.50
Rank	1	2	3	1	2	3

9 competitors in Tier 1.

6 competitors in Tier 2.

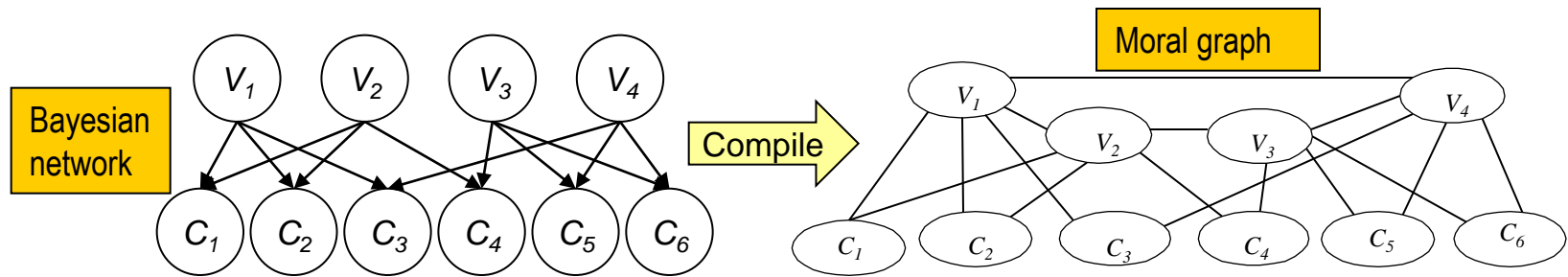
Scalability of Bayesian Network Computation

Bipartite Bayesian Networks



The number of sensors in mobile devices and infrastructure have increased dramatically. Are we taking full advantage of them, to understand the behavior of users as well as the communication and computation infrastructure?

Clique Tree Clustering

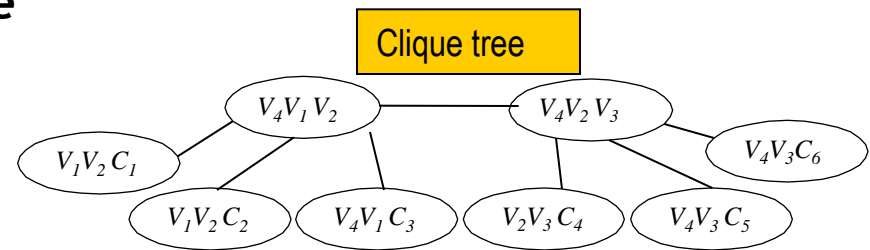
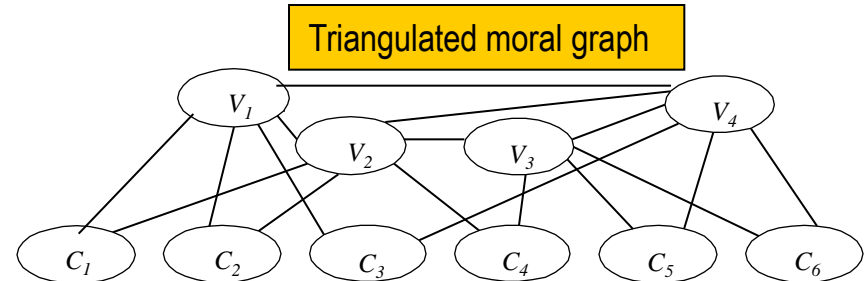


Tree clustering: a major approach to BN inference

Tree clustering algorithms employ two phases:

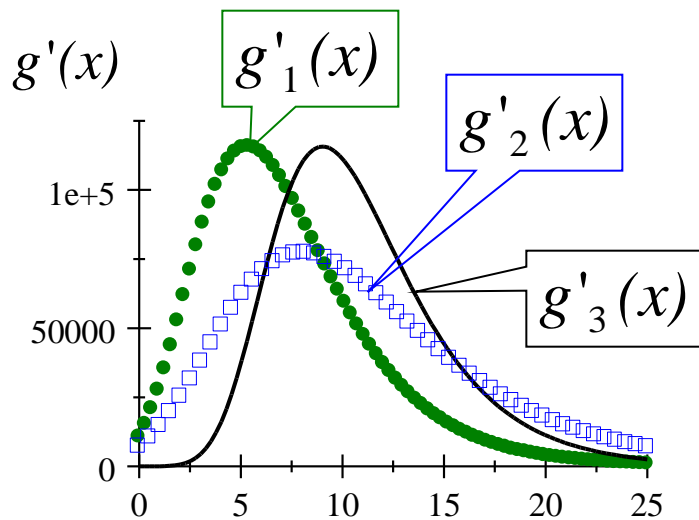
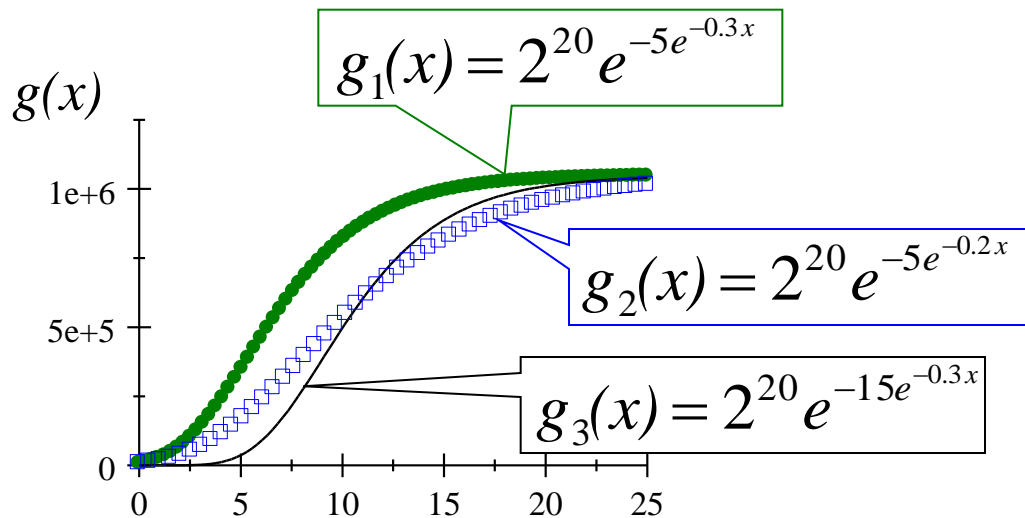
Compilation: generate clique tree B''' from BN B

Propagation: do belief revision (MPEs) or belief updating (marginals) by propagation of evidence in B'''



Details in [Lauritzen & Spiegelhalter, 88].

Gompertz Growth Curves



Gompertz growth curve:

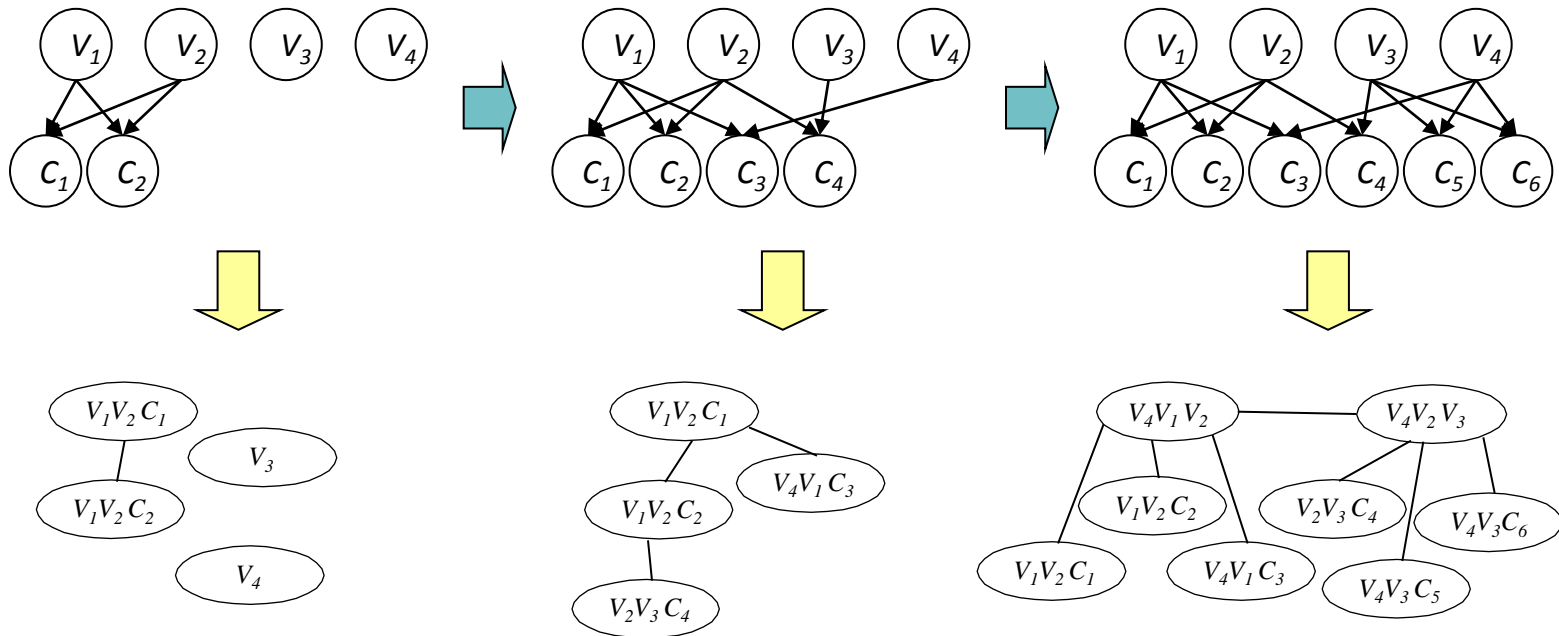
$$g(x) = g(\infty) e^{-\zeta e^{-\gamma x}}$$

$g_1(x)$ to $g_3(x)$: Shift growth curve to right by increasing ζ from $\zeta = 5$ to $\zeta = 15$.

$g_1(x)$ to $g_2(x)$: Decrease maximal growth rate by decreasing γ from $\gamma = 0.3$ to $\gamma = 0.2$.

Growth of Bayesian Networks

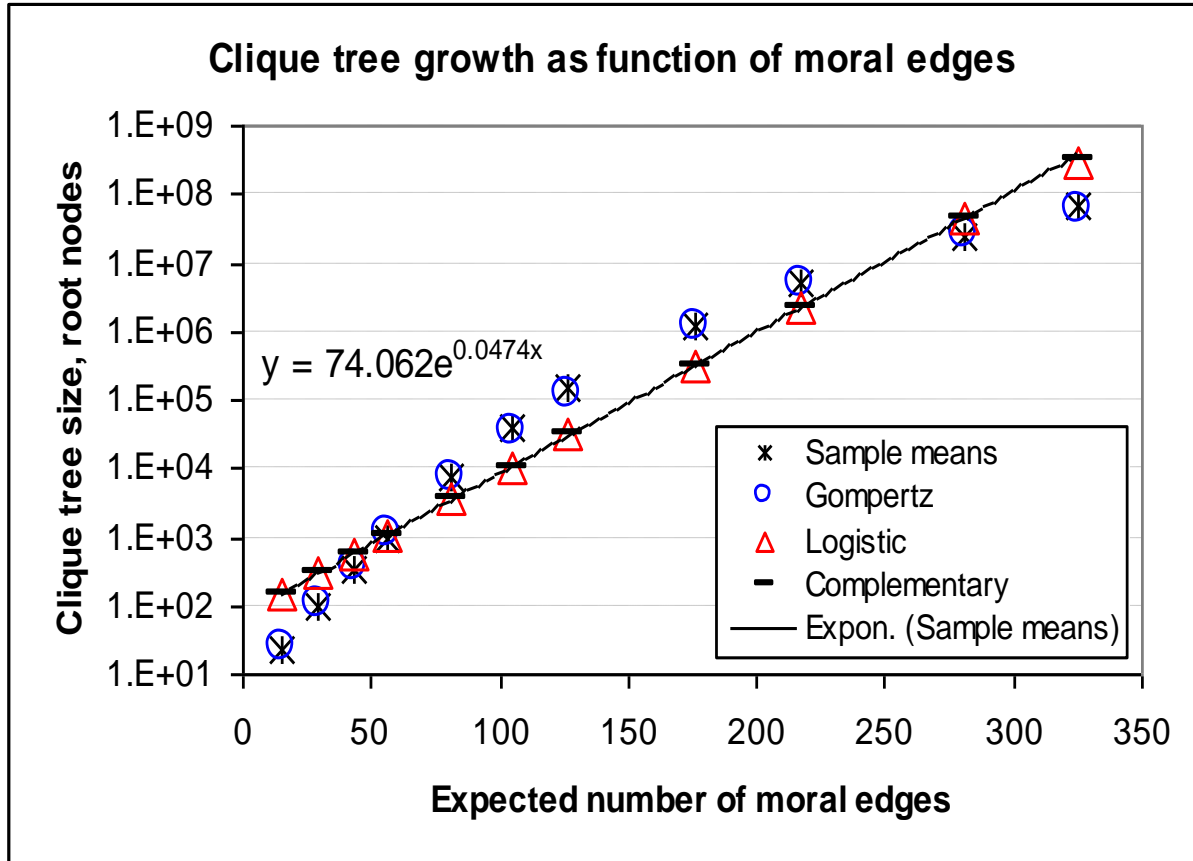
Number of sensors - Bayesian network leaf nodes



Total Gompertz growth curve for BPART(V, C, P, S):

$$g_T(x) = S^V e^{-\zeta e^{-\lambda x}} + xS^{P+1}$$

Comparing Growth Curves



BNs of varying hardness generated with parameters $V=30$, $S=2$, $P=2$, and varying C .

Gompertz growth curve:

$$g(x) = 2^{30} \times \exp(-19.14 \times \exp(-0.005874x))$$

Current and Planned Work

Analytics:

- Improve Expectation Maximization (EM) algorithms for Bayesian network parameter estimation – exploit parallelism in modern hardware and software architectures
- Approach 1: Develop EM layer "on top of" improved GPU-based approach to junction tree propagation
- Approach 2: Use MapReduce to explore data parallelism in Bayesian network parameter

Visualization:

- Improvements to current multi-focus, multi-view network visualizations
- Integration of novel and existing of analytics and visualization techniques

Experiments, demonstrations, and software:

- ADAPT datasets and Bayesian networks
- Synthetic Bayesian networks ("similar to ADAPT") and other Bayesian networks
- Other network data sets: VAST challenge; disaster and emergency management, social network data, ...
- Hardening and distribution of Java software

Publications

- A. Choi, L. Zheng, A. Darwiche, and O. J. Mengshoel. “A Tutorial on Bayesian Networks for System Health Management’,” In *Machine Learning and Knowledge Discovery for Engineering Systems Health Management*, Chapman & Hall/CRC Data Mining and Knowledge Discovery Series, A. N. Srivastava and J. Han (Editors) , 2011.
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Questions?